

# Package ‘RcppDynProg’

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**Type** Package

**Title** 'Rcpp' Dynamic Programming

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**URL** <https://github.com/WinVector/RcppDynProg/>,  
<https://winvector.github.io/RcppDynProg/>

**BugReports** <https://github.com/WinVector/RcppDynProg/issues>

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## Description

Dynamic Programming implemented in 'Rcpp'. Includes example partition and out of sample fitting applications. Also supplies additional custom coders for the 'vtreat' package.

**License** GPL-2 | GPL-3

**Depends** R (>= 3.4.0)

**Imports** wrapr (>= 2.0.4), Rcpp (>= 1.0.0), utils, stats

**LinkingTo** Rcpp, RcppArmadillo

**RoxygenNote** 7.2.3

**Suggests** tinytest, knitr, rmarkdown

**VignetteBuilder** knitr

**NeedsCompilation** yes

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**Repository** CRAN

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**R topics documented:**

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RcppDynProg-package    *RcppDynProg*

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**Description**

Rcpp dynamic programming solutions for partitioning and machine learning problems. Includes out of sample fitting applications. Also supplies additional custom coders for the vtreat package. Please see <https://github.com/WinVector/RcppDynProg> for details.

**Author(s)**

John Mount

**See Also**

Useful links:

- <https://github.com/WinVector/RcppDynProg/>
- <https://winvector.github.io/RcppDynProg/>
- Report bugs at <https://github.com/WinVector/RcppDynProg/issues>

---

|             |                    |
|-------------|--------------------|
| const_costs | <i>const_costs</i> |
|-------------|--------------------|

---

**Description**

Built matrix of total out of sample interval square error costs for held-out means. One indexed.

**Usage**

```
const_costs(y, w, min_seg, indices)
```

**Arguments**

|         |  |
|---------|--|
| y       | NumericVector, values to group in order.             |
| w       | NumericVector, weights.                              |
| min_seg | positive integer, minimum segment size ( $\geq 1$ ). |
| indices | IntegerVector, order list of indices to pair.        |

**Value**

xcosts NumericMatix, for  $j \geq i$  xcosts(i,j) is the cost of partition element [i,...,j] (inclusive).

**Examples**

```
const_costs(c(1, 1, 2, 2), c(1, 1, 1, 1), 1, 1:4)
```

---

|                      |                             |
|----------------------|-----------------------------|
| const_costs_logistic | <i>const_costs_logistic</i> |
|----------------------|-----------------------------|

---

**Description**

Built matrix of interval logistic costs for held-out means. One indexed.

**Usage**

```
const_costs_logistic(y, w, min_seg, indices)
```

**Arguments**

|         |  |
|---------|--|
| y       | NumericVector, 0/1 values to group in order (should be in interval [0,1]). |
| w       | NumericVector, weights (should be positive).                               |
| min_seg | positive integer, minimum segment size ( $\geq 1$ ).                       |
| indices | IntegerVector, order list of indices to pair.                              |

**Value**

`xcosts` NumericMatrix, for  $j \geq i$  `xcosts(i,j)` is the cost of partition element  $[i, \dots, j]$  (inclusive).

**Examples**

```
const_costs_logistic(c(0.1, 0.1, 0.2, 0.2), c(1, 1, 1, 1), 1, 1:4)
```

---

`lin_costs`

*lin\_costs*

---

**Description**

Built matrix of interval costs for held-out linear models. One indexed.

**Usage**

```
lin_costs(x, y, w, min_seg, indices)
```

**Arguments**

|                      |  |
|----------------------|--|
| <code>x</code>       | NumericVector, x-coords of values to group.          |
| <code>y</code>       | NumericVector, values to group in order.             |
| <code>w</code>       | NumericVector, weights.                              |
| <code>min_seg</code> | positive integer, minimum segment size ( $\geq 1$ ). |
| <code>indices</code> | IntegerVector, ordered list of indices to pair.      |

**Value**

`xcosts` NumericMatrix, for  $j \geq i$  `xcosts(i,j)` is the cost of partition element  $[i, \dots, j]$  (inclusive).

**Examples**

```
lin_costs(c(1, 2, 3, 4), c(1, 2, 2, 1), c(1, 1, 1, 1), 1, 1:4)
```

---

lin\_costs\_logistic      *lin\_costs\_logistic deviance costs.*

---

### Description

Built matrix of interval deviance costs for held-out logistic models. Fits are evaluated in-sample. One indexed.

### Usage

```
lin_costs_logistic(x, y, w, min_seg, indices)
```

### Arguments

|         |  |
|---------|--|
| x       | NumericVector, x-coords of values to group.                            |
| y       | NumericVector, values to group in order (should be in interval [0,1]). |
| w       | NumericVector, weights (should be positive).                           |
| min_seg | positive integer, minimum segment size ( $\geq 1$ ).                   |
| indices | IntegerVector, ordered list of indices to pair.                        |

### Value

xcosts NumericMatix, for  $j \geq i$  xcosts(i,j) is the cost of partition element [i,...j] (inclusive).

### Examples

```
lin_costs_logistic(c(1, 2, 3, 4, 5, 6, 7), c(0, 0, 1, 0, 1, 1, 0), c(1, 1, 1, 1, 1, 1, 1), 3, 1:7)
```

---

piecewise\_constant      *Piecewise constant fit.*

---

### Description

vtreat custom coder based on RcppDynProg::solve\_for\_partition().

### Usage

```
piecewise_constant(varName, x, y, w = NULL)
```

**Arguments**

|         |   |
|---------|---|
| varName | character, name of variable to work on. |
| x       | numeric, input values.                  |
| y       | numeric, values to estimate.            |
| w       | numeric, weights.                       |

**Examples**

```
piecewise_constant("x", 1:8, c(-1, -1, -1, -1, 1, 1, 1, 1))
```

---

```
piecewise_constant_coder
```

*Piecewise constant fit coder factory.*

---

**Description**

Build a piecewise constant fit coder with some parameters bound in.

**Usage**

```
piecewise_constant_coder(
  penalty = 1,
  min_n_to_chunk = 1000,
  min_seg = 10,
  max_k = 1000
)
```

**Arguments**

|                |   |
|----------------|---|
| penalty        | per-segment cost penalty.               |
| min_n_to_chunk | minimum n to subdivied problem.         |
| min_seg        | positive integer, minimum segment size. |
| max_k          | maximum segments to divide into.        |

**Value**

a vtreat coder

**Examples**

```
coder <- piecewise_constant_coder(min_seg = 1)
coder("x", 1:8, c(-1, -1, -1, -1, 1, 1, 1, 1))
```

---

piecewise\_linear      *Piecewise linear fit.*

---

**Description**

vtreat custom coder based on RcppDynProg::solve\_for\_partition().

**Usage**

```
piecewise_linear(varName, x, y, w = NULL)
```

**Arguments**

|         |   |
|---------|---|
| varName | character, name of variable to work on. |
| x       | numeric, input values.                  |
| y       | numeric, values to estimate.            |
| w       | numeric, weights.                       |

**Examples**

```
piecewise_linear("x", 1:8, c(1, 2, 3, 4, 4, 3, 2, 1))
```

---

piecewise\_linear\_coder  
*Piecewise linear fit coder factory.*

---

**Description**

Build a piecewise linear fit coder with some parameters bound in.

**Usage**

```
piecewise_linear_coder(  
  penalty = 1,  
  min_n_to_chunk = 1000,  
  min_seg = 10,  
  max_k = 1000  
)
```

**Arguments**

penalty            per-segment cost penalty.  
 min\_n\_to\_chunk    minimum n to subdivied problem.  
 min\_seg            positive integer, minimum segment size.  
 max\_k              maximum segments to divide into.

**Value**

a vtreat coder

**Examples**

```
coder <- piecewise_linear_coder(min_seg = 1)
coder("x", 1:8, c(1, 2, 3, 4, 4, 3, 2, 1))
```

---

score\_solution            *compute the price of a partition solution (and check is valid).*

---

**Description**

compute the price of a partition solution (and check is valid).

**Usage**

```
score_solution(x, solution)
```

**Arguments**

x                    NumericMatix, for  $j \geq i$   $x(i,j)$  is the cost of partition element  $[i, \dots, j]$  (inclusive).  
 solution            vector of indices

**Value**

price

**Examples**

```
x <- matrix(c(1,1,5,1,1,0,5,0,1), nrow=3)
s <- c(1, 2, 4)
score_solution(x, s)
```



---

solve\_for\_partition    *Solve for a piecewise linear partition.*

---

### Description

Solve for a good set of right-exclusive x-cuts such that the overall graph of  $y \sim x$  is well-approximated by a piecewise linear function. Solution is a ready for use with `base::findInterval()` and `stats::approx()` (demonstrated in the examples).

### Usage

```
solve_for_partition(  
  x,  
  y,  
  ...,  
  w = NULL,  
  penalty = 0,  
  min_n_to_chunk = 1000,  
  min_seg = 1,  
  max_k = length(x)  
)
```

### Arguments

|                |  |
|----------------|--|
| x              | numeric, input variable (no NAs).                      |
| y              | numeric, result variable (no NAs, same length as x).   |
| ...            | not used, force later arguments by name.               |
| w              | numeric, weights (no NAs, positive, same length as x). |
| penalty        | per-segment cost penalty.                              |
| min_n_to_chunk | minimum n to subdivided problem.                       |
| min_seg        | positive integer, minimum segment size.                |
| max_k          | maximum segments to divide into.                       |

### Value

a data frame appropriate for `stats::approx()`.

### Examples

```
# example data  
d <- data.frame(  
  x = 1:8,  
  y = c(1, 2, 3, 4, 4, 3, 2, 1))  
  
# solve for break points
```

```

soln <- solve_for_partition(d$x, d$y)
# show solution
print(soln)

# label each point
d$group <- base::findInterval(
  d$x,
  soln$x[soln$what=='left'])
# apply piecewise approximation
d$estimate <- stats::approx(
  soln$x,
  soln$pred,
  xout = d$x,
  method = 'linear',
  rule = 2)$y
# show result
print(d)

```

---

solve\_for\_partitionc    *Solve for a piecewise constant partiton.*

---

## Description

Solve for a good set of right-exclusive x-cuts such that the overall graph of  $y \sim x$  is well-approximated by a piecewise linear function. Solution is a ready for use with `base::findInterval()` and `stats::approx()` (demonstrated in the examples).

## Usage

```

solve_for_partitionc(
  x,
  y,
  ...,
  w = NULL,
  penalty = 0,
  min_n_to_chunk = 1000,
  min_seg = 1,
  max_k = length(x)
)

```

## Arguments

|     |  |
|-----|--|
| x   | numeric, input variable (no NAs).                      |
| y   | numeric, result variable (no NAs, same length as x).   |
| ... | not used, force later arguments by name.               |
| w   | numeric, weights (no NAs, positive, same length as x). |

penalty            per-segment cost penalty.  
 min\_n\_to\_chunk    minimum n to subdivied problem.  
 min\_seg            positive integer, minimum segment size.  
 max\_k              maximum segments to divide into.

### Value

a data frame appropriate for stats::approx().

### Examples

```
# example data
d <- data.frame(
  x = 1:8,
  y = c(-1, -1, -1, -1, 1, 1, 1, 1))

# solve for break points
soln <- solve_for_partitionc(d$x, d$y)
# show solution
print(soln)

# label each point
d$group <- base::findInterval(
  d$x,
  soln$x[soln$what=='left'])
# apply piecewise approximation
d$estimate <- stats::approx(
  soln$x,
  soln$pred,
  xout = d$x,
  method = 'constant',
  rule = 2)$y
# show result
print(d)
```

---

solve\_interval\_partition

*solve\_interval\_partition interval partition problem.*

---

### Description

Solve a for a minimal cost partition of the integers  $[1, \dots, \text{nrow}(x)]$  problem where for  $j \geq i$   $x(i, j)$  is the cost of choosing the partition element  $[i, \dots, j]$ . Returned solution is an ordered vector  $v$  of length  $k \leq k_{\max}$  where:  $v[1] = 1$ ,  $v[k] = \text{nrow}(x) + 1$ , and the partition is of the form  $[v[i], v[i+1])$  (intervals open on the right).

**Usage**

```
solve_interval_partition(x, kmax)
```

**Arguments**

**x** square NumericMatix, for  $j \geq i$   $x(i,j)$  is the cost of partition element  $[i, \dots, j]$  (inclusive).

**kmax** int, maximum number of segments in solution.

**Value**

dynamic program solution.

**Examples**

```
costs <- matrix(c(1.5, NA ,NA ,1 ,0 , NA, 5, -1, 1), nrow = 3)
solve_interval_partition(costs, nrow(costs))
```

---

solve\_interval\_partition\_k

*solve\_interval\_partition interval partition problem with a bound on number of steps.*

---

**Description**

Solve a for a minimal cost partition of the integers  $[1, \dots, \text{nrow}(x)]$  problem where for  $j \geq i$   $x(i,j)$  is the cost of choosing the partition element  $[i, \dots, j]$ . Returned solution is an ordered vector  $v$  of length  $k \leq kmax$  where:  $v[1] == 1$ ,  $v[k] == \text{nrow}(x) + 1$ , and the partition is of the form  $[v[i], v[i+1])$  (intervals open on the right).

**Usage**

```
solve_interval_partition_k(x, kmax)
```

**Arguments**

**x** square NumericMatix, for  $j \geq i$   $x(i,j)$  is the cost of partition element  $[i, \dots, j]$  (inclusive).

**kmax** int, maximum number of segments in solution.

**Value**

dynamic program solution.

**Examples**

```
costs <- matrix(c(1.5, NA ,NA ,1 ,0 , NA, 5, -1, 1), nrow = 3)
solve_interval_partition(costs, nrow(costs))
```

---

```
solve_interval_partition_no_k
      solve_interval_partition interval partition problem, no bound on the
      number of steps.
```

---

**Description**

Not working yet.

**Usage**

```
solve_interval_partition_no_k(x)
```

**Arguments**

`x` square NumericMatrix, for  $j \geq i$   $x(i,j)$  is the cost of partition element  $[i, \dots, j]$  (inclusive).

**Details**

Solve a for a minimal cost partition of the integers  $[1, \dots, \text{nrow}(x)]$  problem where for  $j \geq i$   $x(i,j)$  is the cost of choosing the partition element  $[i, \dots, j]$ . Returned solution is an ordered vector  $v$  of length  $k$  where:  $v[1] == 1$ ,  $v[k] == \text{nrow}(x) + 1$ , and the partition is of the form  $[v[i], v[i+1])$  (intervals open on the right).

**Value**

dynamic program solution.

**Examples**

```
costs <- matrix(c(1.5, NA ,NA ,1 ,0 , NA, 5, -1, 1), nrow = 3)
solve_interval_partition(costs, nrow(costs))
```

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